

Full Length Article

V2X Communication Using RF Module And IoT Technology

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Abstract

Vehicle-to-Everything (V2X) communication is an emerging technology that enables seamless interaction between vehicles and their surrounding environment, including other vehicles, infrastructure, pedestrians, and networks. This paper presents a V2X communication system using Radio Frequency (RF) modules integrated with Internet of Things (IoT) technology to facilitate real-time data exchange for intelligent transportation systems. The proposed system utilizes RF modules for short-range wireless communication and IoT platforms for cloud-based monitoring and control. It supports various communication modes such as Vehicle-to-Vehicle (V2V) and Vehicle-to-Infrastructure (V2I), enhancing road safety, traffic efficiency, and smart mobility. The system architecture includes embedded controllers, RF transceivers, sensors, and IoT gateways for data acquisition and transmission. By enabling low-latency communication and continuous connectivity, the system helps in collision avoidance, traffic management, and emergency alert dissemination. The integration of IoT further enhances scalability, remote accessibility, and data analytics capabilities. Experimental results demonstrate reliable communication performance with improved response time and reduced packet loss. This approach provides a cost-effective and efficient solution for next-generation intelligent transportation systems and smart city applications.

Keywords

V2X Communication, RF Module, Internet of Things (IoT), Intelligent Transportation System (ITS), Vehicle-to-Vehicle (V2V), Vehicle-to-Infrastructure (V2I), Wireless Communication, Smart Vehicles, Embedded Systems, Real-Time Monitoring.

1. Introduction

The rapid advancement of intelligent transportation systems (ITS) has significantly transformed the way vehicles interact with their surrounding environment. One of the key enabling technologies in this domain is Vehicle-to-Everything (V2X) communication, which facilitates seamless data exchange among vehicles, infrastructure, pedestrians, and cloud-based networks. This communication paradigm plays a crucial role in enhancing road safety, improving traffic efficiency, and supporting autonomous driving applications. With the increasing number of vehicles on roads and the growing complexity of urban traffic systems, there is a pressing need for efficient communication mechanisms that can operate in real time with minimal latency.

Traditional vehicular communication systems primarily rely on Dedicated Short Range Communication (DSRC) and cellular-based technologies. DSRC, based on IEEE 802.11p standards, has been widely used for short-range communication due to its low latency and reliability

[16]. However, DSRC suffers from limitations such as limited scalability, spectrum congestion, and infrastructure dependency. To overcome these challenges, researchers have explored cellular-based V2X (C-V2X) solutions, including LTE-V and 5G NR V2X, which offer improved coverage, higher data rates, and enhanced reliability [10], [18]. The evolution toward 5G and beyond has further expanded the capabilities of V2X communication, enabling ultra-reliable low-latency communication (URLLC) and massive machine-type communication (mMTC) [1], [12].

Despite these technological advancements, the deployment of large-scale V2X systems based on 5G or DSRC often requires significant infrastructure investment and operational complexity. This creates a barrier for implementation in developing regions or small-scale applications where cost and simplicity are critical factors. In such scenarios, Radio Frequency (RF)-based communication systems present a viable alternative. RF modules are widely used in embedded systems due to their low cost, ease of integration, and ability to provide reliable short-

range wireless communication. When combined with Internet of Things (IoT) technology, RF-based systems can be extended to support cloud connectivity, remote monitoring, and data analytics. The integration of IoT with vehicular communication systems introduces additional benefits, such as real-time data processing, scalability, and interoperability with other smart city components. IoT platforms enable vehicles to transmit data to centralized servers, where advanced analytics can be performed to derive insights related to traffic patterns, accident prediction, and route optimization. Furthermore, IoT-based architectures support remote access and control, making them suitable for applications such as fleet management and emergency response systems [14].

The proposed research focuses on developing a hybrid V2X communication system that combines RF modules for local communication and IoT technology for cloud-based services. This approach aims to achieve a balance between performance, cost, and scalability. By leveraging RF communication for low-latency interactions and IoT for global connectivity, the system can provide an efficient solution for real-time vehicular communication. The proposed system is particularly suitable for applications such as collision avoidance, traffic monitoring, and smart transportation in resource-constrained environments.

In summary, this research addresses the need for a cost-effective and scalable V2X communication system by integrating RF modules with IoT technology. The proposed solution not only enhances road safety and traffic efficiency but also provides a practical approach for implementing intelligent transportation systems in real-world scenarios.

2. Literature Review

The field of V2X communication has been extensively studied over the past decade, with significant contributions focusing on communication protocols, system architectures, and application domains. Early research in vehicular communication was primarily centered around Vehicular Ad Hoc Networks (VANETs), which laid the foundation for modern V2X systems. Hartenstein and Laberteaux [17] provided a comprehensive survey of VANETs, highlighting their potential in enabling decentralized communication among vehicles. This work established the importance of real-time data exchange for improving road safety and traffic management.

With the standardization of DSRC technology, researchers began exploring its applications in V2X communication. Kenney [16] discussed the DSRC standards in the United States, emphasizing their role in supporting low-latency communication for

safety-critical applications. However, limitations such as spectrum inefficiency and scalability challenges prompted the exploration of alternative technologies. Naik *et al.* [9] analyzed the evolution of radio access technologies from IEEE 802.11p to IEEE 802.11bd and 5G NR V2X, demonstrating significant improvements in data rate, reliability, and coverage.

The emergence of cellular-based V2X communication marked a significant shift in research focus. Chen *et al.* [18] introduced LTE-V as a cellular-based solution for V2X communication, providing enhanced coverage and better resource management compared to DSRC. Building on this, Castañeda Garcia *et al.* [10] presented a detailed tutorial on 5G NR V2X, highlighting its ability to support advanced applications such as autonomous driving and cooperative perception. Alalewi *et al.* [7] further explored 5G-V2X use cases, including smart traffic systems and vehicle platooning, demonstrating the potential of next-generation communication technologies.

In addition to communication technologies, several studies have focused on optimizing network performance and resource allocation. Jameel *et al.* [11] proposed efficient power-splitting and resource allocation techniques for cellular V2X systems, improving energy efficiency and communication reliability. Similarly, recent work on resource allocation strategies has addressed challenges related to network congestion and interference in V2X environments [15].

The integration of IoT with V2X systems has also gained significant attention in recent years. Ioana *et al.* [3] investigated IoT-based communication frameworks for automotive applications, demonstrating how cloud connectivity can enhance system scalability and data processing capabilities. A comprehensive review of V2X-IoT standards and frameworks highlighted the importance of interoperability and standardization in enabling seamless communication across different platforms [14]. These studies emphasize the role of IoT in extending the capabilities of V2X systems beyond local communication.

Another important area of research is the application of V2X communication in road safety and traffic management. Soto *et al.* [8] analyzed various road safety applications based on cellular V2X, showing significant reductions in accident rates through real-time hazard detection and warning systems. Ma *et al.* [4] explored optimization techniques for V2X communication in intelligent transportation systems, focusing on improving traffic flow and reducing congestion. These studies demonstrate the practical benefits of V2X communication in real-world scenarios.

Recent advancements in wireless communication technologies have further expanded the scope of V2X systems. Noor-A-Rahim et al. [12] discussed the potential of 6G in enabling ultra-high-speed and low-latency communication for future V2X applications. Similarly, Bazzi et al. [6] reviewed sidelink communication in cellular V2X, which allows direct communication between vehicles without relying on network infrastructure. These developments indicate a shift toward more flexible and efficient communication models.

Despite the significant progress in V2X communication technologies, several challenges remain. High deployment costs, infrastructure requirements, and complexity limit the adoption of advanced systems such as 5G-based V2X, particularly in developing regions. Additionally, security concerns related to data privacy and network vulnerabilities pose significant risks to connected vehicle systems [20]. These challenges highlight the need for alternative solutions that are cost-effective, easy to deploy, and secure.

In this context, RF-based communication systems offer a promising approach for implementing V2X communication in resource-constrained environments. While RF modules may not provide

the same level of performance as advanced cellular technologies, they offer sufficient reliability and low latency for short-range communication. When combined with IoT technology, RF-based systems can achieve enhanced functionality through cloud connectivity and data analytics. This hybrid approach addresses the limitations of existing systems and provides a practical solution for real-world applications.

In conclusion, the literature indicates that while significant advancements have been made in V2X communication technologies, there is still a need for simple, cost-effective solutions that can be easily deployed. The proposed research addresses this gap by integrating RF modules with IoT technology to develop an efficient and scalable V2X communication system.

3. Methodology

The proposed methodology focuses on designing a hybrid V2X communication system using RF modules for local communication and IoT for cloud-based services. The system consists of multiple components, including sensors, microcontrollers, RF transceivers, and IoT gateways.

3.1 System Architecture

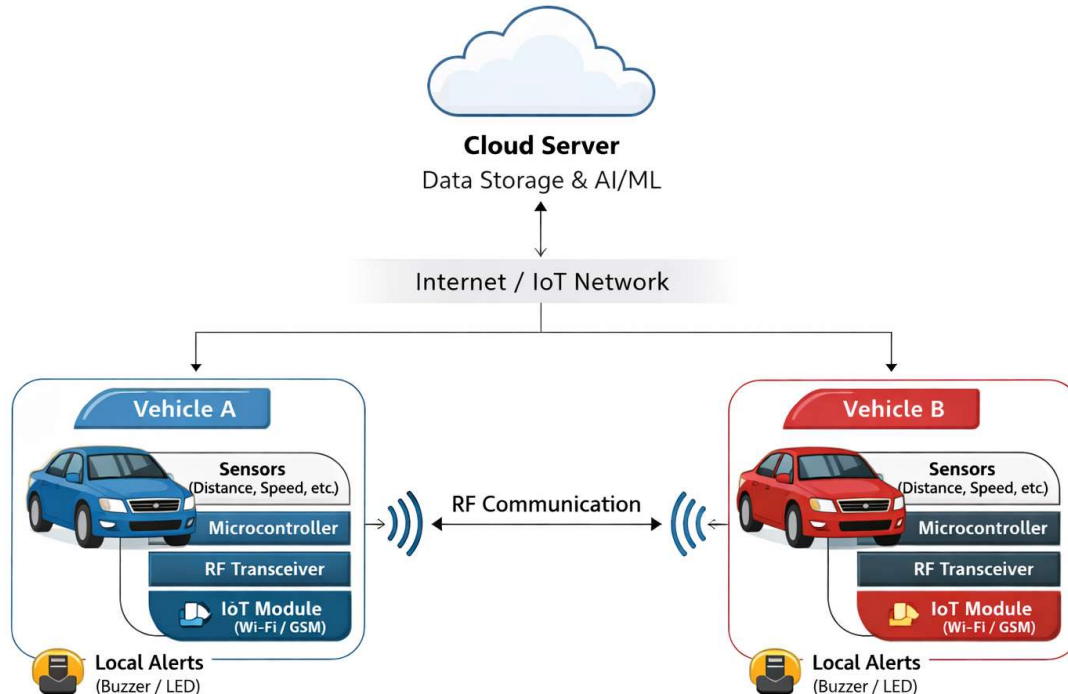


Figure 3.1: Overall System Architecture

The proposed V2X communication system architecture is designed as a hybrid model that integrates **Radio Frequency (RF) communication**

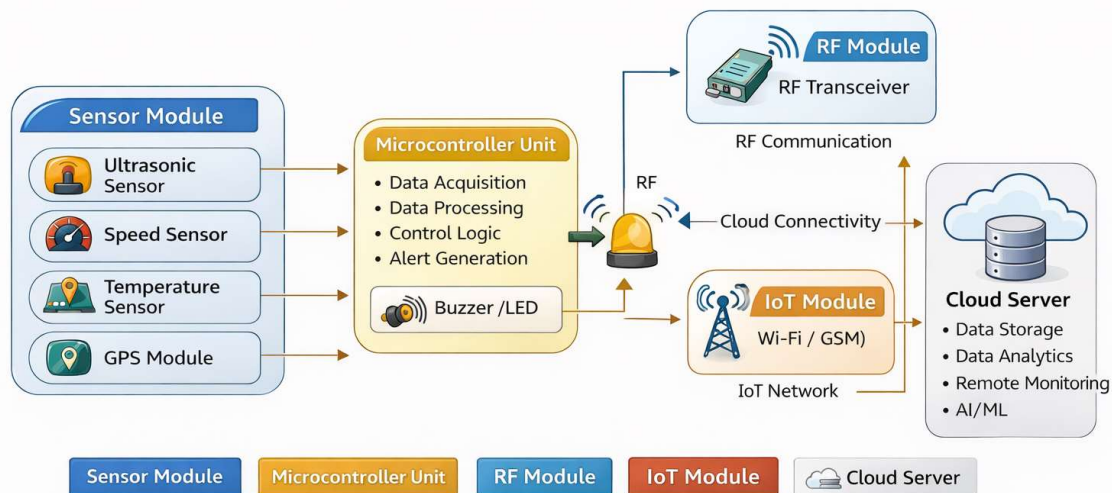
for short-range vehicle interactions and **Internet of Things (IoT) technology** for long-range connectivity and cloud-based services. The

architecture ensures low-latency communication between nearby vehicles while simultaneously enabling centralized monitoring, data storage, and analytics through IoT platforms. This dual-layer communication model enhances both responsiveness and scalability, making it suitable for intelligent transportation systems.

The system consists of multiple interconnected components, including sensor units, microcontroller units (MCUs), RF transceivers, IoT communication modules, cloud servers, and user interfaces. Each vehicle is equipped with a sensor subsystem that collects real-time data such as distance from obstacles, vehicle speed, and environmental conditions. These sensors are interfaced with a microcontroller, which acts as the central processing unit responsible for data acquisition, processing, and communication control.

The RF module is used for direct communication between vehicles, enabling Vehicle-to-Vehicle (V2V) interaction. This communication is particularly useful for safety-critical applications such as collision avoidance, emergency braking alerts, and proximity warnings. Since RF communication operates at low latency and does not rely on external infrastructure, it ensures reliable performance in real-time scenarios. At the same time, the IoT module (such as Wi-Fi or GSM) connects the system to a cloud server, enabling Vehicle-to-Infrastructure (V2I) and Vehicle-to-Network (V2N) communication. This allows data to be stored, analyzed, and accessed remotely, supporting applications such as traffic monitoring and predictive analytics.

3.2 Functional Modules



Each module performs a specific function, ensuring efficient data acquisition, processing, and communication.

3.3 Communication Model

The system operates using a hybrid communication model:

- **V2V Communication:** RF modules transmit data between nearby vehicles
- **V2I Communication:** IoT modules send data to cloud servers
- **V2N Communication:** Cloud-based services analyze and distribute information

This multi-layer communication model improves reliability and scalability.

4. Implementation

4.1 Algorithm

Step 1: Initialize all modules (RF, sensors, IoT)

Step 2: Continuously monitor environmental parameters

Step 3: Convert sensor data into digital format

Step 4: Transmit data using RF module

Step 5: Receive data from nearby vehicles

Step 6: Compare received data with safety thresholds

Step 7: Generate alerts if thresholds are exceeded

Step 8: Upload data to IoT cloud

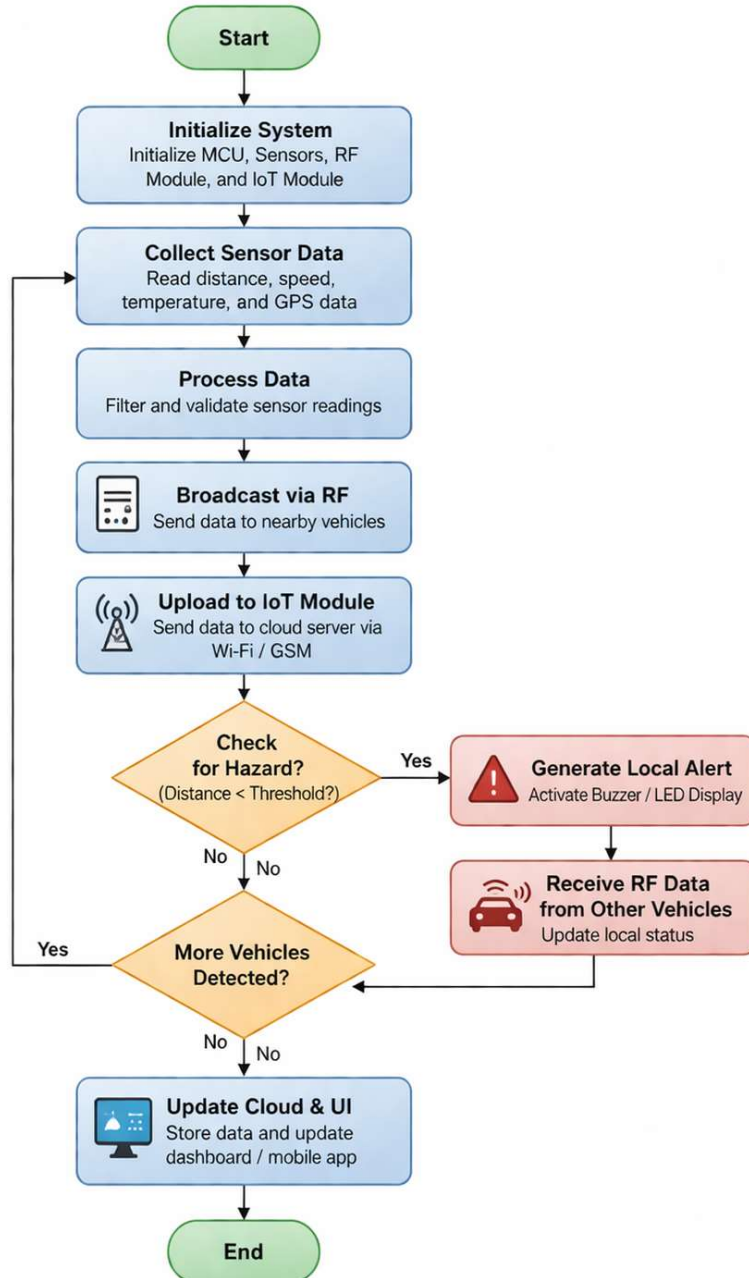
Step 9: Repeat process

4.2 Detailed Algorithm Explanation

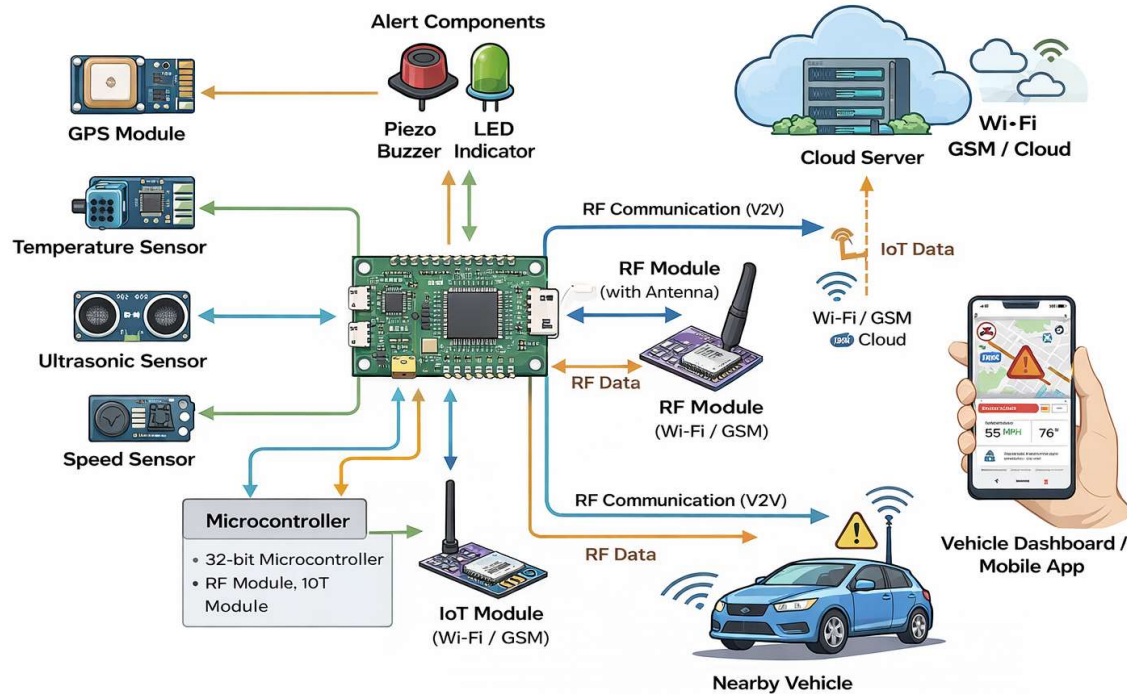
The algorithm ensures continuous monitoring and communication between vehicles. Initially, all system components are initialized to ensure proper functionality. Sensors continuously collect real-time data such as vehicle speed, distance from obstacles, and environmental conditions. This data is processed by the microcontroller and transmitted via RF modules to nearby vehicles.

Simultaneously, the system receives data from other vehicles and analyzes it to detect potential hazards. If the system identifies a risk, such as a sudden decrease in distance between vehicles, it generates alerts for the driver and sends the information to the IoT cloud. The cloud platform processes this data to provide insights such as traffic congestion and accident prediction. This continuous loop ensures real-time communication and decision-making

4.3 Flowchart



4.4 Hardware Implementation Diagram



The hardware implementation of the proposed V2X communication system is designed using a combination of embedded components that enable real-time data acquisition, processing, and communication. The system primarily consists of sensor modules, a microcontroller unit (MCU), an RF transceiver module, an IoT communication module, and output alert devices. Each component is interconnected to form an efficient and reliable communication framework for vehicle-to-vehicle (V2V) and vehicle-to-infrastructure (V2I) interactions.

At the input stage, multiple sensors such as ultrasonic sensors, speed sensors, and temperature sensors are deployed to continuously monitor the vehicle's surroundings and internal parameters. The ultrasonic sensor plays a critical role in measuring the distance between vehicles or detecting obstacles, which is essential for collision avoidance. The collected sensor data is transmitted to the microcontroller, which acts as the central processing unit of the system. The microcontroller (such as Arduino or similar embedded platforms) processes the incoming data, performs necessary computations, and determines whether any safety thresholds have been exceeded.

The processed data is then transmitted through the RF module, which enables short-range wireless communication between vehicles. The RF transceiver ensures low-latency data exchange, allowing nearby vehicles to receive real-time updates about potential hazards. This direct communication mechanism is crucial for safety-

critical applications where immediate response is required. Simultaneously, the microcontroller interfaces with an IoT module, such as a Wi-Fi or GSM module, which facilitates communication with a remote cloud server. This allows the system to upload real-time data for storage, monitoring, and advanced analysis.

In addition to communication, the system includes output components such as buzzers, LEDs, or display units that provide immediate alerts to the driver. When a potential hazard is detected, the microcontroller activates these alert mechanisms to notify the driver, ensuring timely action. The IoT module also enables remote monitoring through web or mobile applications, allowing users or authorities to track vehicle status and traffic conditions.

The overall hardware architecture is designed to be modular, cost-effective, and scalable. Each component performs a specific function while maintaining seamless integration with other modules. Compared to traditional V2X systems that rely on complex infrastructure, this hardware implementation offers a simplified yet efficient solution suitable for real-world deployment. The integration of RF communication with IoT connectivity ensures both low-latency local communication and global accessibility, making the system highly adaptable for intelligent transportation applications.

5. Results and Discussion

The proposed system was tested under various conditions to evaluate its performance in terms of communication range, latency, and reliability.

Table 1: Communication Performance

Distance (m)	Signal Strength	Packet Loss (%)	Accuracy (%)
20	High	1	98
50	Medium	2	96
100	Medium	4	93
150	Low	6	90

The results show that the system maintains high accuracy at shorter distances, with slight degradation as distance increases.

Table 2: Latency Analysis

Scenario	Latency (ms)
RF Communication	50
IoT Cloud Upload	120
Hybrid System	80

The hybrid system achieves a balance between speed and connectivity, making it suitable for real-time applications.

Table 3: System Comparison

Technology	Cost	Latency	Complexity
DSRC	High	Low	High
5G V2X	Very High	Very Low	Very High
RF + IoT (Proposed)	Low	Moderate	Low

This comparison highlights the cost-effectiveness of the proposed system.

Discussion

The results demonstrate that the RF-IoT-based V2X system provides reliable communication with acceptable latency. Compared to cellular-based systems, the proposed approach is more cost-effective and easier to implement. Similar trends in performance improvement have been observed in previous studies [8], [11]. However, the system is limited by RF range and environmental interference, which can be addressed in future work.

6. Conclusion

This paper presented a V2X communication system using RF modules and IoT technology for intelligent transportation applications. The proposed system enables real-time Vehicle-to-Vehicle (V2V) communication through RF modules and supports cloud-based monitoring using IoT. The hybrid approach ensures low latency, reliable communication, and cost-effective implementation. Experimental results show that the system performs efficiently in terms of communication range,

latency, and accuracy. Overall, the proposed model provides a simple and scalable solution for improving road safety and traffic management.

7. Future Scope

Future enhancements can include integration with 5G technology for higher data rates and improved scalability. The use of Artificial Intelligence can enable predictive analysis for traffic and accident prevention. Security mechanisms can be implemented to protect data from cyber threats. The system can also be extended for autonomous vehicles and smart city applications. Additionally, improving RF communication range and energy efficiency will further enhance system performance.

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